MVE5xxR



Globe Valves Actuators with Emergency Fail-safe Function

| MODEL CODE | ORDERING CODE | FORCE [N] | POWER SUPPLY | DESCRIPTION | |
|---------------|------------------|--------------|--|--|---|
| MVE504R | 1373xx | 400 | | Long yoke, modulating/ | |
| MVE506R | 1373xx | 600 | 24 V | floating control with position emergency | |
| MVE510R | 1373xx | 1000 | AC/DC | return with totally open or closed valve selectable | |
| MVE515R | 1373xx | 1500 | | through jumper | |
| MVE504SR | 1373xx | 400 | | Short yoke, modulating/ | |
| MVE506SR | 1373xx | 600 | 24 V position emer AC/DC return with tota or closed valve so | floating control with position emergency | |
| MVE510SR | 1373xx | 1000 | | | return with totally open or closed valve selectable |
| MVE515SR | 1373xx | 1500 | | through jumper | |



APPLICATION AND USE

MVE5xxR is a flexible electro-mechanical actuator equipped with an electronic fail safe function for the control of two-way and three-way globe valves in:

- Heating and cooling systems;
- Air Handling Units;
- District heating plants;
- · Industrial temperature control systems.

The actuator is endowed with an electronic emergency return function which operates through the use of ultracapacitors whose life is about 10 years if the actuator operates within the operation limits declared in this data sheet.

The emergency position (retracted or extended stem) is set through the use of a jumper which can be easily reached (look at paragraph "DIP switches and jumper settings").

The actuator is supplied with totally discharged ultracapacitors and at its first start a pre-charge phase of 130s max will be necessary. N.B.: in this condition during the first 20-30s no LED signal on the upper ultracapacitors control board will be revealed; when this interval has elapsed the RED LED will power on (ultracapacitors charging phase, look at table on page 7).

During this phase all the functions of the actuator are inhibited and the charge status of the ultracapacitors is signalled through 2 LEDs (look at paragraph "Standard LEDs behaviour").

MVE5xxR can be controlled either by a proportional (modulating) signal or by an increase/decrease (floating) signal.

It is easy to mount and connect the actuator. The actuator has a fine resolution (500 steps on the full stroke range) for accurate fluid control and it is able to self-calibrate on a different stroke without the need of any user action (this function is DIP switch selectable on the field).

MVE5xxR has intelligent behavior and alarm functionality in case of unexpected operation, feedback of alarms to the user is provided by LEDs (GREEN and RED) on the actuator upper control board.

N.B.: do not use the actuator if not coupled with its relating valve.

TECHNICAL CHARACTERISTICS

| DESCRIZIONE | MVE504R MVE504SR | MVE506R MVE506SR | MVE510R MVE510SR | MVE515R MVE515SR | |
|--|---------------------|-------------------------|--------------------------|---------------------|--|
| Supply voltage L1 Ln | AC: 2 | 4 V AC ±20% 50-60 Hz; [| DC:22-30 V DC (Reference | ce Ln) | |
| Power consumption (running) | 10 VA/4,5 W | 13 VA/6 W | 18 VA/8 W | 21 VA/11 W | |
| Power consumption (Holding) | 8 VA/4 W | 11 VA/5 W | 11 VA/5 W | 13 VA/7 W | |
| Charging phase consumption | 32 VA/18 W | | | | |
| Ultracapacitors charging phase (if totally discharged) | 130 s | | | | |
| Running and emergency return time | | 1,1 s. | /mm | | |

The performances stated in this sheet can be modified without any prior notice.



| DESCRIZIONE | | MVE504R MVE504SR | MVE506R MVE506SR | MVE510R MVE510SR | MVE515R MVE515SR | | |
|-------------------|---------------------|---|---------------------|---------------------|---------------------|--|--|
| | | 18 s (for valves with stroke 16,5 mm) | | | | | |
| Running | Modulating | 28 s (for valves with stroke 25 mm) | | | | | |
| time | | | 50 s (for valves w | ith stroke 45 mm) | | | |
| | Floating | | 60 s | | | | |
| Transf | former Size [VA] | 20 | 50 | 60 | 80 | | |
| | Stroke | | 5-60 mm (limited to | 30mm for MVE.SR) | | | |
| | Force | 400 N | 600 N | 1000 N | 1500 N | | |
| | Duty cycle | | Max 50%/6 | 50 minutes | | | |
| Analo | ogue input Y M | Voltage 0-10 V - impedance > 100 kΩ (range: 0-10 V DC, 2-10 V DC, 0-5/2-6 V DC, 5-10/6-10 V DC) 500 Ω (range 4-20 mA) | | | | | |
| Digit | al inputs Y1 Y2 | Connection to L1 or Ln when powered in AC; connection to Ln only when powered in DC | | | | | |
| Output V+ | | Voltage 16 V DC ± 0,5 V; max load 25mA | | | | | |
| Output U | | Voltage 2-10 V DC (0-100%); max load 2 mA; voltage 1 V DC (during the emergency return phase) | | | | | |
| Number of | cycles of emergency | 1.000 | | | | | |
| Туре | e of movement | Linear | | | | | |
| Ambie | ent temperature | Operation -10T55°C; storage -20T55°C | | | | | |
| Amb | pient Humidity | Max 90% RH | | | | | |
| Protection degree | | IP54 (with PG13,5 cable gland - not supplied) | | | | | |
| Insulation class | | (n)> | | | | | |
| Standard | | Emission/Immunity EMC 2014/30/UE according to EN 61326-1:2013 standard | | | | | |
| Material | | Housing: aluminium - cover: ABS plastic | | | | | |
| Colour | | Aluminium / white | | | | | |
| Weight [kg] | | | 1,7 (MVE5xxR); | 1,6 (MVE5xxSR) | | | |

OPERATION

The actuator is endowed with an electronic emergency fail safe function which, in case of power failure, allows to close (or to open) the valve and to go back to the set position through the jumper.

The actuator commutes the control signal (modulating or 3-point floating) from the controller into a valve position. A modern brushless DC motor in the actuator drives a gear train and a worm gear – screw jack mechanism convert the motor revolutions into accurate and repeatable linear movements.

Control Signal

MVE5xxR can be controlled by one of 2 main control types.

- 3-point floating;
- Modulating (proportional) signal with filed selectable range (e.g., 0-10 V DC, 2-10 V DC, 0-5/2-6 V DC, 5-10/6-10 V DC and 4-20 mA).

Manual Override

There is a manual operation handle on the actuator. When it is lowered (manual override ON), the power supply to the motor power stage circuitry is cut and the motor stops. The actuator can be operated manually and the valve positioned accordingly.

The manual override lever stays in position until it is raised again, then board and motor will be powered again. At the end of this operation the actuator moves to initial position (on the basis of DIP 1 setting) then it follows the control signal. When the manual override is engaged the GREEN and the RED LED on the lower electronic board are ON.

Manual operation handle can also be used to modify any DIP switch setting or as re-set function after any alarm occurrence.

The actuator is supplied with the manual override lowered (ON). It is not necessary to remove power supply to modify DIP switches setting.

Feedback Position

The actuator provides a feedback signal of:

- 2-10 V DC in direct or reverse action (look at DIP n. 1 settings)
- 1Vdc during the emergency return phase



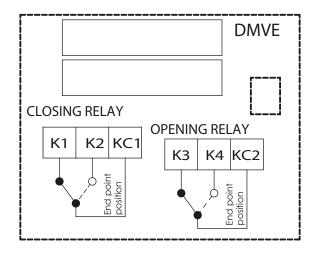
Calibration

MVE5xxR is endowed with an automatic stroke calibration function, but it can be calibrated also manually. The actuator is delivered with DIP n. 7 set to auto. Manual calibration is not necessary unless maintenance is required on the valve or certain alarm functions are desired.

End Point Auxiliary Switches (accessory DMVE)

End point switches change over when the valve is fully open or closed. They are free contacts with 24 V AC/DC, 4 A max voltage on terminals. End point switches can be utilized to indicate valve stroke end positions and for relay control of additional plant equipment. When the actuators are controlled individually or in sequence, it is possible to use the end switches to toggle when the valve is fully open or fully closed. The auxiliary switch position according to control signal (Y) is shown in the picture below.

| CONTROL SIGNAL (Y) | RELAY KC1 | RELAY KC2 |
|--------------------|-----------|-----------|
| 0-0,5 V DC | KC1 to K2 | KC2 to K3 |
| 0,5-9,5 V DC | KC1 to K1 | KC2 to K3 |
| 9,5-10 V DC | KC1 to K1 | KC2 to K4 |



Diagnostic

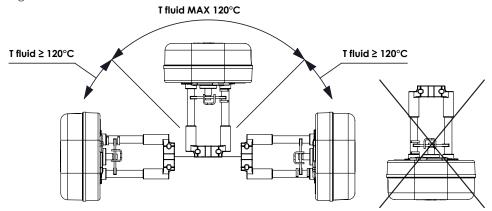
The actuator is provided with a self diagnostic algorithm able to detect faulty conditions:

- stroke calibration out of range 5-60 mm;
- unexpected stall condition (e.g. valve stuck or extra stroke due to actuator link loose);
- voltage supply out of range.

These faulty conditions are signalled via the GREEN and RED LED on the lower electronic board blinking accordingly (see "Diagnostic – Alarm Function Table").

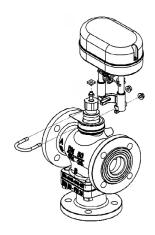
ASSEMBLING

The actuator can be mounted with any orientation but never up-side down. When the fluid temperature exceed 120°C the actuator shall be mounted leaning 45°.



To mount the actuator on to a valve, position the valve stem to the bottom of its travel, slide the actuator onto the valve neck, adjusting with the manual override the screw jack position so the square nut on the valve spindle fits into the groove on the cross bar. Then slide the brace into the groove on the valve neck and secure the nuts.





See mounting instructions for full details.

MAINTENANCE

The actuator is maintenance-free.

ACCESSORIES

DMVE Endpoint auxiliary switches (electrical rate 24 V AC/DC, 4 A)

GMVE Thermal insulation for MVE actuators * **GMVES** Thermal insulation for MVE.S actuators *

KIT-P13.5 10 cable glands kit (nuts and gaskets included)

KIT-T13.5 Kit 10 caps for cable glands hole (nuts and gaskets included)

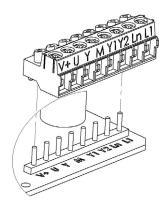
248 Stem heater (suggested when the fluid temperature is below 0°C) *

ELECTRICAL CONNECTIONS

Remove the cover screw with a screwdriver and then remove the cover as shown in the picture below.

The actuator is equipped with a 8 poles removable terminal block; each pole of the plug is clearly marked and the same label are reported on the electronic board. Before powering up the actuator make sure the plug is properly connected to the board and the label on the plugs and on the board match.





Use PG13,5 cable gland (not supplied).

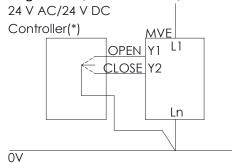


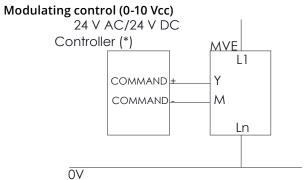
^{*} It is not possible to install both thermal insulation (Gxxxx) and stem heaters.

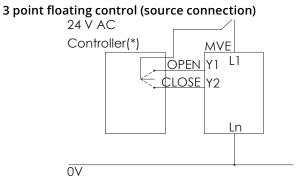
| LABEL | DESCRIPTION | FUNCTION | CABLE TYPE | MAX. WIRE LENGTH | |
|-------|-----------------|--------------------------|--|------------------|--|
| L1 | 24 V AC/DC | Power supply | AWG 16 | 75 m | |
| Ln | 0 V | rowei suppiy | (min 1mm² - max 1,5mm²) | | |
| Υ | 0-10 V DC | | AWG 20 | | |
| М | 0 V (common) | Modulating control input | (min 0,5mm2 - max 1,5mm2) | 200 m | |
| Y1 | Open | Floating control input | AWG 20 | 200 m | |
| Y2 | Close | Floating Control Input | (min 0,5mm² - max 1,5mm²) | 200111 | |
| V+ | 16 V DC | | AWG 20 | | |
| М | 0 V (common) | Voltage output max 25 mA | (min 0,5mm ² - max 1,5mm ²) | 200 m | |
| U | 2-10 V DC* | | AWG 20 | | |
| М | 0 V (common) | Feedback output signal | (min 0,5mm ² - max 1,5mm ²) | 200 m | |

^{* 1}Vdc during the emergency return phase

3 point floating control (sink connection)



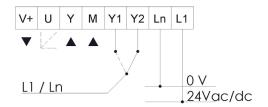




N.B.: M and Ln signals are internally connected.

(*) MVE contain a single half-wave rectifier power supply. They must not be powered with transformers that are used to power other devices using not isolated double half-wave rectifier power supply.

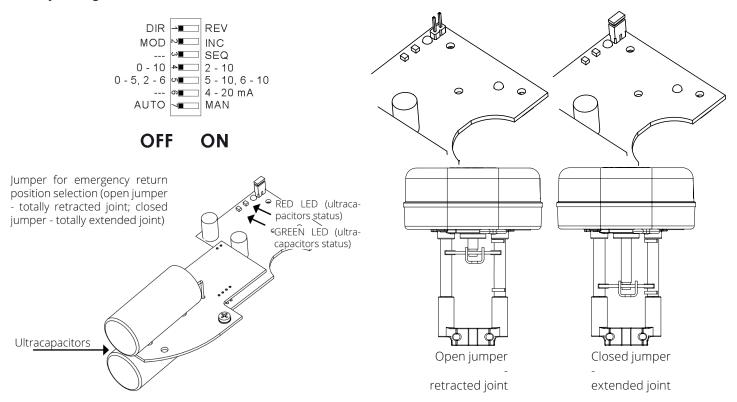
TERMINAL BLOCK





Set the DIP switches according to the tables here below. In order to be sure that any modification has been accepted by the actuator, power down and power up it again or act on the manual operation handle to be sure that settings will be recognized.

Factory settings



| DIP SWITCH | OFF | ON | | |
|------------|--|---|--|--|
| | Direct Action | Reverse Action | | |
| 1 | U= feedback U = 2V U = 10V | U = 10V U = 2V | | |
| | Modulating Control (MOD) (Input between Y [+] and M [-]) | 3 point floating (INC) (Y1 open-extend , Y2 close-re- tract connected L1 or Ln if powered in Vac; if powe- red in Vdc connected necessarily to Ln) | | |
| 2 | | Y1 Y2 | | |
| 3 | - | Selection of sequence mode, control range defined by DIP n. 5 | | |
| 4 | Modulating Control 0-10 V DC (DIP n. 2 OFF only) | Modulating Control 2-10 V DC (DIP n. 2 OFF only) | | |
| 5 | Sequence Control 0-5 V DC with DIP n. 4 OFF only Sequence Control 2-6 V DC with DIP n. 4 ON only (DIP n. 3 ON only) | Sequence Control 5-10 V DC with DIP n. 4 OFF only Sequence Control 6-10 V DC with DIP n. 4 ON only (DIP n. 3 ON only) | | |
| 6 | Voltage Input Signal (input between Y [+] and M [-]) | Current Input Signal 4-20 mA (input between Y [+] and M [-]). In this case DIP n. 4 must be set to ON. | | |
| 7 | Automatic Calibration: the actuator updates the stroke range every time an unexpected mechanical stop is detected for at least 10s | Manual Calibration: the actuator calibration is started moving the DIP from OFF to ON or vice versa. With DIP in ON in case of extra stroke or if an unexpected endpoint is detected, the actuator will never update the stroke | | |



| | LEDS ACTUATOR | | ACTUATOR B | ACTUATOR BEHAVIOUR | | | |
|----|--|---|--|---|---|--|--|
| N° | LEDS BEHAVIOUR | ERROR | ACTUATOR USE | AUTOMATIC CALIBRATION (DIP N. 7 OFF) | MANUAL CALIBRATION (DIP N. 7 ON) | TROUBLE SHOOTING CONDITION | RESET PROCEDURE |
| 1 | RED ON | Valve stroke less than 5mm | Calibration/ first installa- tion | The actuator pushes/pulls 2 times (unexpected stall) trying to remove the possible obstacle. After 2 tries an alarm is signalled and the actuator moves to initial position and does not respond to control signal. Stroke value is not updated because out of range | The actuator pushes/ pulls 2 times against endpoint during calibration and the actuator moves to the initial position and then it does not respond to the control signal. The actuator keeps the previous stroke | Valve with a stroke length lower than 5mm | Remove power and power up again |
| 2 | RED LED quick blinking + GREEN ON | Stroke longer than 60mm | Calibration/ first installa- tion | The actuator exits the 60mm stroke range and it moves toward the new stroke limit signalling an anomaly. The actuator pushes/pulls 2 times against the new stroke limit, then it goes back to the initial position still signalling the anomaly until it is not within 60mm. The actuator does not calibrate the stroke after 10s (wrong range) | The actuator exits the 60mm stroke range and it moves toward the new stroke limit signalling an anomaly. The actuator pushes/pulls 2 times against the new stroke limit, then it goes back to the initial position still signalling the anomaly until it is not within 60mm. The actuator does not calibrate the stroke after 10s (wrong range) | Valve with a stroke len- gth longer than 60mm | Remove power and power up again |
| 3 | RED Quick Blinking | Unexpected stall within the calibra- ted stroke range | normal ope- ration | The actuator tries 5 times against the new stall condition and then after 10s the actuator updates the new stroke length | The actuator tries 5 times against the new stall condition. At the end of the attempts the fault will be signalled. The actuator does not update the new stroke length, but after 60s makes other attempts to verify the stall condition | Valve stuck | Inverted con- trol signal |
| 4 | RED Quick Blinking | Stroke longer than expected | Normal ope- ration | The actuator moves toward the new stall condition with a lower speed; after 10s the actuator updates the new stroke value | The actuator moves toward the new stall condition with a lower speed; after 10s the actuator does not upda- te the new stroke value | Stem con- nection lo- ose or valve damaged | Inverted con- trol signal |
| 5 | 5 RED slow Blinking | Low Power Normal ope- Voltage ration | The actuator is still working but performance cannot | The actuator is still working but performance | 1. Wrong transformer size | Correct Volta- ge Power | |
| | | | | be guaranteed | cannot be guaranteed | 2. Unstable power | <i>G</i> - 2 · · · · · |
| 6 | 6 RED slow Blinking | | The actuator is still working but performance cannot | The actuator is still working but performance | 1. Wrong transformer size | Correct Volta- ge Power | |
| | | | 70106 | be guaranteed | cannot be guaranteed | 2. Unstable power | 0 1 14 |

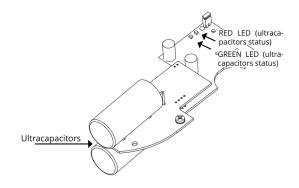


Lower electronic board

| N° | LED | ACTUATOR STATUS | |
|----|------------------------------------|---|--|
| 1 | GREEN ON | The actuator arrived at the extreme point of the stroke | |
| 2 | GREEN BLINKING | The actuator is moving or arrived at the intermediate point of the stroke | |
| 3 | RED GREEN BLINKING ALTERNATING | Calibration or initialization phase | |
| 4 | RED GREEN ON | Manual control enabled, the actuators ignores the control signal ATTENTION! The electronic board is electrically supplied | |
| 5 | RED GREEN BLINKING SIMULTANEOUS | The actuator is in emergency return phase | |

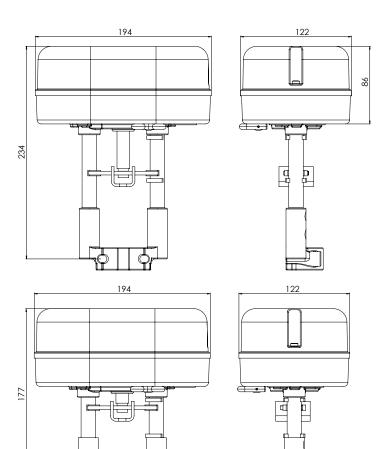
Upper electronic board

| LED | ULTRACAPACITORS STATUS |
|-------|------------------------------------|
| GREEN | Ultracapacitors charged |
| RED | Ultracapacitors discharging |
| OFF | Ultracapacitors totally discharged |



DIMENSIONS [mm]

MVE



MVE.S

